

Contents :

Front Matter

- Preface
- Contributors

Section I – Introduction

Chapter 1. Sensor-Based Planning and Control for Robotic Systems: An Event-Based Approach

- Introduction
- Event-based planning and control
- Event-based motion planning for robot manipulators
- Multirobot coordination
- System implementation
- Conclusions

Section II – Visually Guided Sensing and Control

Chapter 2. Observer-Based Visual Servoing

Chapter 3. Active Deformable Models in Visual Servoing

Chapter 4. Visually Guided Tracking and Manipulation

These chapters address:

- Visual servo control
- Image-based feedback
- Camera modeling
- Robot vision
- Object tracking
- Feature extraction
- Motion estimation
- Vision-guided manipulation
- Nonlinear visual control

Section III – Multiple Sensor Fusion in Planning and Control

Chapter 5. Complementary Sensor Fusion in Robotic Manipulation

Chapter 6. Feedback Control with Force and Visual Sensor Fusion

Chapter 7. Sensor-Referenced Impact Control in Robotics

Topics include:

- Multi-sensor fusion
- Force and vision integration
- Tactile sensing
- Hybrid position–force control
- Sensor fusion algorithms
- Impact dynamics
- Robust impact control
- Switching control
- Experimental validation

Section IV – System Integration, Modeling, and Controller Design

Chapter 8. A Modular Approach to Sensor Integration

Chapter 9. A Circuit-Theoretic Analysis of Robot Dynamics and Control

Chapter 10. Sensor-Based Planning and Control in Telerobotics

Main topics:

- Modular sensor architectures
- System integration
- Robot dynamics
- Nonlinear control
- Passivity
- Impedance matching
- Learning and adaptation
- Telerobotics
- Remote manipulation
- Teleoperation
- Three-dimensional task planning

Section V – Applications

Chapter 11. Automated Integration of Multiple Sensors

Chapter 12. Robotics with Perception and Action Nets

Chapter 13. A Fuzzy Behaviorist Approach to Sensor-Based Reasoning and Robot Navigation

Applications covered include:

- Automated sensor integration
- Perception–action architectures
- Intelligent robot control
- Autonomous navigation
- Sensor anomaly detection
- Uncertainty management
- Error recovery
- Planetary robotics
- Fuzzy reasoning
- Mobile robot navigation

Back Matter

- References (at the end of each chapter)
- Index