
CONTENTS

PREFACE, xi

1. BASIC CONTROL SYSTEM CONCEPTS, 1

- 1.1 Introduction, 2
- 1.2 A History of Control Systems, 4
- 1.3 System Configurations, 8
- 1.4 Analysis and Design Objectives, 10
 - Introduction to a Case Study, 12
- 1.5 The Design Process, 15
- 1.6 Computer-Aided Design, 20
- 1.7 The Control Systems Engineer, 22
 - Summary, 23
 - Review Questions, 23
 - Problems, 24
 - Progressive Analysis and Design Problems, 28
 - Bibliography, 29

2. TRANSFER FUNCTIONS OF PHYSICAL SYSTEMS, 31

- 2.1 Introduction, 32
- 2.2 Laplace Transform Review, 32
- 2.3 The Transfer Function, 42
- 2.4 Electrical Network Transfer Functions, 45
- 2.5 Translational Mechanical System Transfer Functions, 59
- 2.6 Rotational Mechanical System Transfer Functions, 66
- 2.7 Transfer Functions for Systems with Gears, 71

2.8 Electromechanical System Transfer Functions, 75

2.9 Electric Circuit Analogs, 81

2.10 Nonlinearities, 84

2.11 Linearization, 85

Case Studies, 90

Summary, 93

Review Questions, 93

Problems, 94

Progressive Analysis and Design

Problems, 105

Cyber Exploration Laboratory, 106

Bibliography, 109

3. STATE EQUATIONS FOR PHYSICAL SYSTEMS, 111

3.1 Introduction, 112

3.2 Some Observations, 112

3.3 The General State-Space Representation, 116

3.4 Applying the State-Space Representation, 118

3.5 Converting a Transfer Function to State Space, 126

3.6 Converting from State Space to a Transfer Function, 133

3.7 Linearization, 135

Case Studies, 138

Summary, 142

Review Questions, 143

Problems, 144

Progressive Analysis and Design Problems, 149
Cyber Exploration Laboratory, 150
Bibliography, 151

4. TRANSIENT RESPONSE, 153

- 4.1 Introduction, 154
- 4.2 Poles, Zeros, and System Response, 154
- 4.3 First-Order Systems, 157
- 4.4 Second-Order Systems: Introduction, 160
- 4.5 The General Second-Order System, 165
- 4.6 Underdamped Second-Order Systems, 168
- 4.7 System Response with Additional Poles, 177
- 4.8 System Response with Zeros, 181
- 4.9 Effects of Nonlinearities upon Time Response, 187
- 4.10 Laplace Transform Solution of State Equations, 190
- 4.11 Time Domain Solution of State Equations, 193
 - Case Studies, 198
 - Summary, 203
 - Review Questions, 205
 - Problems, 206
 - Design Problems, 215
 - Progressive Analysis and Design Problems, 217
 - Cyber Exploration Laboratory, 218
 - Bibliography, 221

5. EQUIVALENT SYSTEMS, 223

- 5.1 Introduction, 224
- 5.2 Block Diagrams, 224
- 5.3 Analysis and Design of Feedback Systems, 233
- 5.4 Signal-Flow Graphs, 236
- 5.5 Mason's Rule, 239
- 5.6 Signal-Flow Graphs of State Equations, 242
- 5.7 Alternative Representations in State Space, 244
- 5.8 Similarity Transformations, 254

Case Studies, 262
Summary, 268
Review Questions, 269
Problems, 270
Design Problems, 283
Progressive Analysis and Design Problems, 284
Cyber Exploration Laboratory, 285
Bibliography, 286

6. TRANSIENT RESPONSE STABILITY, 287

- 6.1 Introduction, 288
- 6.2 Routh-Hurwitz Criterion, 291
- 6.3 Routh-Hurwitz Criterion: Special Cases, 294
- 6.4 Routh-Hurwitz Criterion: Additional Examples, 300
- 6.5 Stability in State Space, 306
 - Case Studies, 309
 - Summary, 311
 - Review Questions, 311
 - Problems, 312
 - Design Problems, 317
 - Progressive Analysis and Design Problems, 319
 - Cyber Exploration Laboratory, 320
 - Bibliography, 321

7. FORCED RESPONSE ERRORS, 323

- 7.1 Introduction, 324
- 7.2 Steady-State Error for Unity Feedback Systems, 327
- 7.3 Static Error Constants and System Type, 333
- 7.4 Steady-State Error Specifications, 337
- 7.5 Steady-State Error for Disturbances, 339
- 7.6 Steady-State Error for Nonunity Feedback Systems, 341
- 7.7 Sensitivity, 345
- 7.8 Steady-State Error for Systems in State Space, 348
 - Case Studies, 352

Summary, 355
 Review Questions, 356
 Problems, 357
 Design Problems, 365
 Progressive Analysis and Design Problems, 367
 Cyber Exploration Laboratory, 368
 Bibliography, 369

8. A GRAPHICAL TOOL, 370

8.1 Introduction, 371
 8.2 Defining the Root Locus, 375
 8.3 Properties of the Root Locus, 378
 8.4 Sketching the Root Locus, 381
 8.5 Refining the Sketch, 386
 8.6 An Example, 395
 8.7 Transient Response Design via Gain Adjustment, 399
 8.8 Generalized Root Locus, 404
 8.9 Root Locus for Positive-Feedback Systems, 405
 8.10 Pole Sensitivity, 408
 Case Studies, 410
 Summary, 416
 Review Questions, 416
 Problems, 417
 Design Problems, 427
 Progressive Analysis and Design Problems, 430
 Cyber Exploration Laboratory, 432
 Bibliography, 433

9. DESIGN USING THE GRAPHICAL TOOL, 435

9.1 Introduction, 436
 9.2 Improving Steady-State Error via Cascade Compensation, 439
 9.3 Improving Transient Response via Cascade Compensation, 449
 9.4 Improving Steady-State Error and Transient Response, 463
 9.5 Feedback Compensation, 476
 9.6 Physical Realization of Compensation, 485

Case Studies, 490
 Summary, 495
 Review Questions, 496
 Problems, 497
 Design Problems, 503
 Progressive Analysis and Design Problems, 510
 Cyber Exploration Laboratory, 510
 Bibliography, 512

10. SINUSOIDAL TOOLS, 513

10.1 Introduction, 514
 10.2 Asymptotic Approximations: Bode Plots, 520
 10.3 Introduction to the Nyquist Criterion, 539
 10.4 Sketching the Nyquist Diagram, 544
 10.5 Stability via the Nyquist Diagram, 549
 10.6 Gain Margin and Phase Margin via the Nyquist Diagram, 553
 10.7 Stability, Gain Margin, and Phase Margin via Bode Plots, 556
 10.8 Relation between Closed-Loop Transient and Closed-Loop Frequency Responses, 559
 10.9 Relation between Closed- and Open-Loop Frequency Responses, 563
 10.10 Relation between Closed-Loop Transient and Open-Loop Frequency Responses, 569
 10.11 Steady-State Error Characteristics from Frequency Response, 573
 10.12 Systems with Time Delay, 577
 10.13 Obtaining Transfer Functions Experimentally, 581
 Case Study, 585
 Summary, 587
 Review Questions, 589
 Problems, 590
 Progressive Analysis and Design Problems, 599
 Cyber Exploration Laboratory, 600
 Bibliography, 601

- 11. DESIGN USING SINUSOIDAL TOOLS, 602**
- 11.1 Introduction, 603
 - 11.2 Transient Response via Gain Adjustment, 604
 - 11.3 Lag Compensation, 607
 - 11.4 Lead Compensation, 612
 - 11.5 Lag-Lead Compensation, 618
 - Case Studies, 622
 - Summary, 625
 - Review Questions, 625
 - Problems, 626
 - Design Problems, 629
 - Progressive Analysis and Design Problems, 631
 - Cyber Exploration Laboratory, 632
 - Bibliography, 633
- 12. DESIGN USING STATE EQUATIONS, 635**
- 12.1 Introduction, 636
 - 12.2 Controller Design, 637
 - 12.3 Controllability, 643
 - 12.4 Alternative Approaches to Controller Design, 648
 - 12.5 Observer Design, 653
 - 12.6 Observability, 660
 - 12.7 Alternative Approaches to Observer Design, 664
 - 12.8 Steady-State Error Design via Integral Control, 671
 - Case Study, 674
 - Summary, 680
 - Review Questions, 681
 - Problems, 682
 - Design Problems, 686
 - Progressive Analysis and Design Problems, 689
 - Cyber Exploration Laboratory, 689
 - Bibliography, 690
- 13. DISCRETE CONTROL SYSTEMS, 692**
- 13.1 Introduction, 693
 - 13.2 Modeling the Digital Computer, 696
 - 13.3 The z -Transform, 699
 - 13.4 Transfer Functions, 704
 - 13.5 Block Diagram Reduction, 708
 - 13.6 Stability, 711
 - 13.7 Steady-State Errors, 718
 - 13.8 Transient Response on the z -Plane, 722
 - 13.9 Gain Design on the z -Plane, 724
 - 13.10 Cascade Compensation via the s -Plane, 728
 - 13.11 Implementing the Digital Compensator, 731
 - Case Studies, 734
 - Summary, 739
 - Review Questions, 740
 - Problems, 741
 - Design Problems, 744
 - Progressive Analysis and Design Problems, 746
 - Cyber Exploration Laboratory, 747
 - Bibliography, 748
- Appendix A List of Symbols, 750**
- Appendix B MATLAB Tutorial, 754**
- Appendix C MATLAB's Simulink Tutorial, 807**
- Glossary, 830**
- Answers to Selected Problems, 839**
- Credits, 845**
- Index, 847**
- Appendix D MATLAB's GUI Tools Tutorial, Web site**
- Appendix E MATLAB's Symbolic Math Toolbox Tutorial, Web site**
- Appendix F Matrices, Determinants, and Systems of Equations, Web site**
- F.1 Matrix Definitions and Notations
 - F.2 Matrix Operations
 - F.3 Matrix and Determinant Identities

**F.4 Systems of Equations
Bibliography**

**Appendix G Control System
Computational
Aids, Web site**

**G.1 Step Response of a System Represented
in State Space**

G.2 Root Locus and Frequency Response

**Appendix H Derivation of a Schematic for
a DC Motor, Web site**

**Appendix I Derivation of the Time
Domain Solution of State
Equations, Web site**

**Appendix J Solution of State Equations
for $t_o \neq 0$, Web site**

**Appendix K Derivation of Similarity
Transformations,
Web site**

**Appendix L Root Locus Rules:
Derivations, Web site**

L.1 Behavior of the Root Locus at Infinity

**L.2 Derivation of Transition Method for
Breakaway and Break-in Points**

**Solutions to Skill-Assessment Exercises,
Web site**

**Control Systems Engineering Toolbox,
Web site**

Lecture Graphics, Web site

**Cyber Exploration Laboratory Experiments,
Web site**

Web site location is www.wiley.com/college/nise.